

TOSHIBA HALL SENSOR GaAs ION IMPLANTED PLANAR TYPE

THS125

HIGH STABILITY MOTOR CONTROL. DIGITAL TACHOMETER.

CRANK SHAFT POSITION SENSOR.

Unit in mm

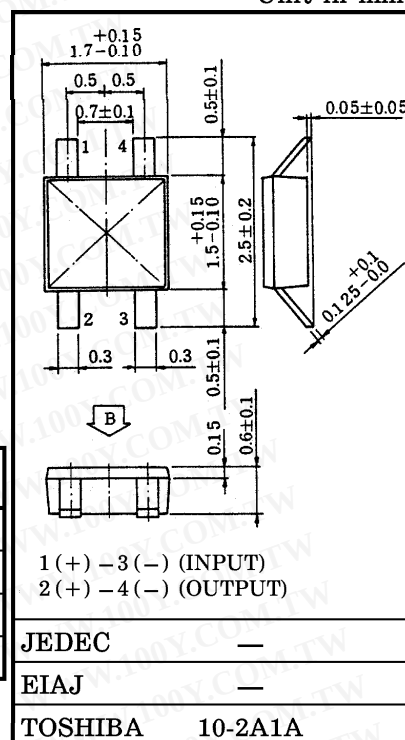
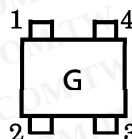
- Super Small Package.
- Excellent Temperature Characteristics.
- Wide Operating Temperature Range. (: $-55\sim 125^{\circ}\text{C}$)
- Excellent Output Voltage Linearity.
- High Internal Resistance. : $R_d = 1000\Omega$ (Min.)
- Low Residual Voltage Ratio. : $V_{HO} / V_H = \pm 5\%$ (Max.)

MAXIMUM RATINGS ($T_a = 25^{\circ}\text{C}$)

CHARACTERISTIC	SYMBOL	RATING	UNIT
Control Voltage	V_C	12**	V
Power Dissipation	P_D	150**	mW
Operating Temperature Range	T_{opr}	$-55\sim 125$	$^{\circ}\text{C}$
Storage Temperature Range	T_{stg}	$-55\sim 150$	$^{\circ}\text{C}$

** Mounted on a printed circuit board.

Marking



Weight : 0.0047g

ELECTRICAL CHARACTERISTICS ($T_a = 25^{\circ}\text{C}$)

CHARACTERISTIC	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT
Internal Resistance (Input)	R_d	$I_C = 1\text{mA}$	1000	1250	1500	Ω
Residual Voltage Ratio	V_{HO} / V_H	$V_C = 5\text{V}, B = 0 / B = 0.1\text{T}$	—	—	± 5	%
Hall Voltage (Note 1)	V_H	$V_C = 5\text{V}, B = 0.1\text{T}$	130	150	170	mV
Temperature Coefficient (Note 2)	V_{HT}	$I_C = 5\text{mA}, B = 0.1\text{T}$ $T_1 = 25^{\circ}\text{C}, T_2 = 125^{\circ}\text{C}$	—	—	-0.06	% / $^{\circ}\text{C}$
Linearity (Note 3)	ΔK_H	$V_C = 5\text{V}, B_1 = 0.05\text{T}, B_2 = 0.1\text{T}$	—	—	2	%
Specific Sensitivity (Note 4)	K^*	$V_C = 5\text{V}, B = 0.1\text{T}$	—	30	—	$\times 10^{-2} / \text{T}$
Internal Resistance (Output)	R_{OUT}	$I_C = 1\text{mA}$	1800	2375	3000	Ω

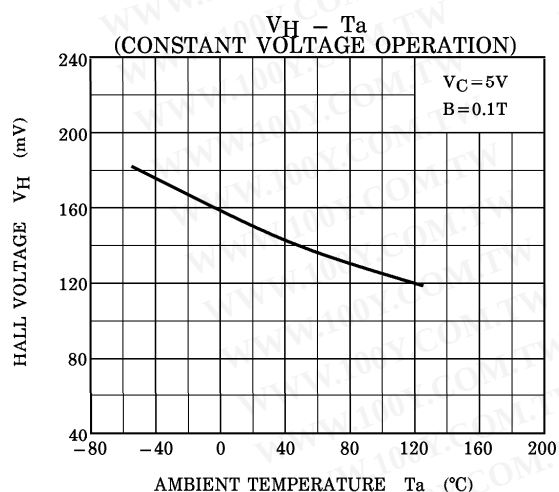
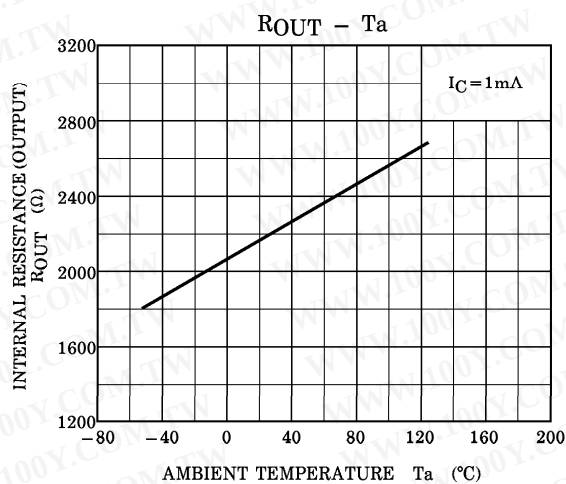
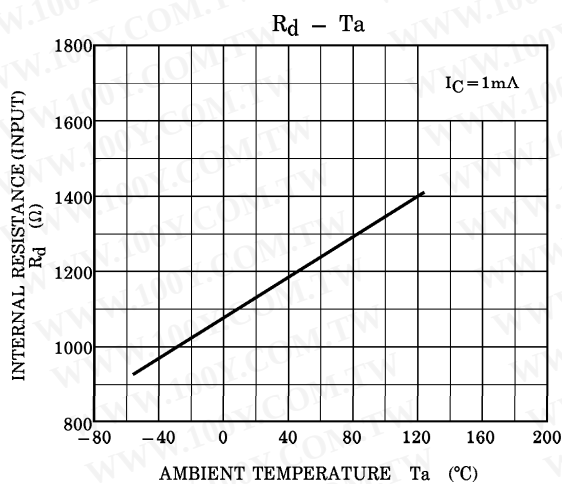
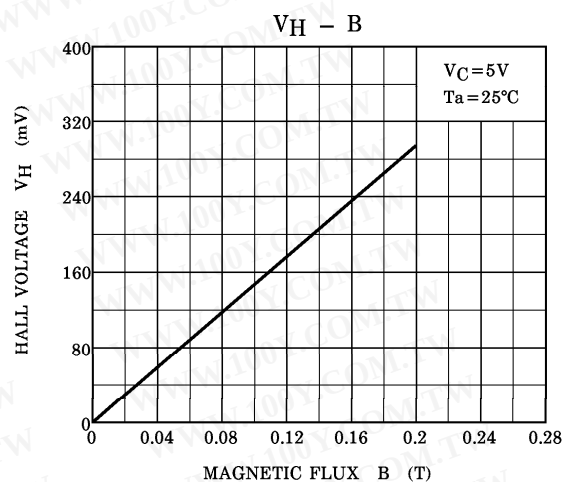
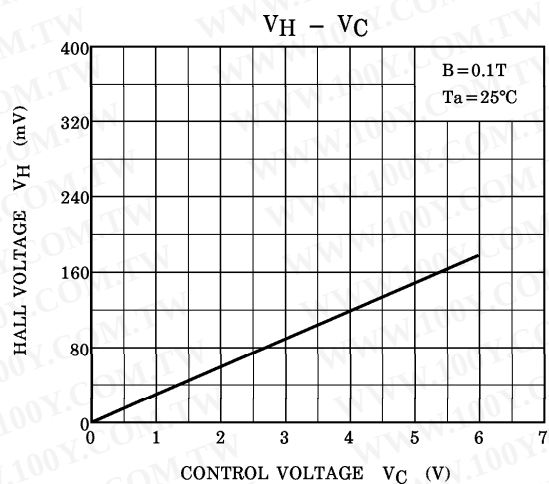
Note 1 : $V_H = V_{HM} - V_{HO}$ (V_{HM} is meter indication)Note 2 : $V_{HT} = \frac{1}{V_H(T_1)} \cdot \frac{V_H(T_2) - V_H(T_1)}{T_2 - T_1} \times 100 (\% / ^{\circ}\text{C})$ V_{HO} : Residual VoltageNote 3 : $\Delta K_H = \frac{K_H(B_2) - K_H(B_1)}{1/2 \{ K_H(B_1) + K_H(B_2) \}} \times 100 (\%)$, $K_H = \frac{V_H}{I_C \cdot B}$ K_H : Product SensitivityNote 4 : $K^* = V_H / (R_d \times I_C \times B) = K_H / R_d$

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